A full example

The idea here is to study the whole process for studying/analyzing a complex problem.

- Description of the problem and modelling
- Complexity study
  - (In)approximation – in case
- Solving the problem:
  - Heuristics and their analysis
- Performance guarantee (Polynomial time approximations)
The story

Let us imagine you have to move fast to a new place and you should store your personal effects in a limited place garage. All your goods are packed into boxes of different sizes (same basis but with different heights).
Theoretical model

- Decision version.

**Bin-Packing**

**Input:** a set of items $A$, a size $s(a)$ for each $a \in A$, a positive integer capacity $C$, and a positive integer $k$

**Question:** is there a partition of $A$ into disjoint sets $A_1, A_2, \ldots, A_k$ such that the total size of the elements in each set $A_j$ does not exceed the capacity $C$, i.e., $\sum_{a \in A_j} s(a) \leq C$?

**Some hypotheses:** the sizes $s(a)$ are integers. No problem to extend to rational numbers.
Example: 9 items and $C = 10$
Let us first prove that \texttt{BinPacking} is in \texttt{NP}-complete.

This is easy by a simple reduction from \texttt{2Partition}. Recall the method.

1. \texttt{BinPacking} $\in \mathcal{NP}$  
   Verifier  
   - given the subset of integers packed in each of the $k$ bins $A_j$, create the sum of these elements and compare with $C$
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2. \textsc{2Partition} $\leq_p \textsc{BinPacking}$
   This is straightforward since \textsc{2Partition} is a subproblem of \textsc{BinPacking} (specific instances with 2 bins)
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We can prove a deeper result (strongly \textbf{NP-complete}):
\textbf{3Partition} $\leq \text{P} \text{ BinPacking}
Inapproximability

**BinPacking** cannot be approximated by a factor better than $3/2$

- Assume by contradiction that it can be approximated by a ratio $\rho < 3/2$
- Apply the gap reduction to a positive instance of $\langle A, C, 2 \rangle$
BinPacking can not be approximated by a factor better than $3/2$

- assume by contradiction that it can be approximated by a ratio $\rho < 3/2$
- apply the gap reduction to a positive instance of $< A, C, 2 >$
- If $OPT(I) \leq 2$ then $SOL(I) \leq 2 \cdot \rho < 3$ then $SOL(I) = 2$

Thus, solving this problem corresponds to solve 2Partition in polynomial time, unless $P = NP$
Approximation ratio: recall

- consider a minimization problem $\Pi$ and a polynomial-time algorithm $A$ for solving this problem
- $OPT(I)$: the objective value of an optimal solution for the instance $I$ of the problem $\Pi$
- $SOL(I)$: the objective value of the solution of our algorithm $A$ for the instance $I$
Approximation ratio: recall

- Consider a minimization problem $\Pi$ and a polynomial-time algorithm $A$ for solving this problem.
- $OPT(\mathcal{I})$: the objective value of an optimal solution for the instance $\mathcal{I}$ of the problem $\Pi$.
- $SOL(\mathcal{I})$: the objective value of the solution of our algorithm $A$ for the instance $\mathcal{I}$.

**Approximation ratio**

\[ SOL(\mathcal{I}) \leq \rho \cdot OPT(\mathcal{I}) \]

- $\rho > 1$
- Note that an approximation is as good as $\rho$ is close to 1.
The notion of approximation can be refined to target the ratio $1 + \epsilon$.

- We are looking for a family of algorithms parametrized by $\epsilon$. 

\[
\text{Polynomial Time Approximation Scheme}\ 
SOL(I) \leq (1 + \epsilon) \cdot \text{OPT}(I) \text{ with running time polynomial in } |I|
\]

- Typically in $O(|I|^{1/\epsilon})$.

- Here, $\epsilon$ is given, thus, the running time is polynomial...
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**Polynomial Time Approximation Scheme**

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with running time polynomial in $|I|$.

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- Here, $\epsilon$ is given, thus, the running time is polynomial...

- We can obtain specific algorithms for some values of $\epsilon$, like $\frac{1}{2}$ or $\frac{1}{3}$
Solving the problem

Take 5 minutes to think at an heuristic.
Solving the problem

Take 5 minutes to think at an heuristic.

Think on the way to operate...

Some ideas:

- proceed bin after bin
- minimum space left in the filled bins
- put the items ASAP
- etc.
Solving the problem: Heuristics

- **Next Fit**
  1. Place each item in a single bin until an item does not fit in
  2. When an item don’t fit, close it and open a new one

- **Best Fit**
  1. Try to place an item in the fullest bin that can accommodate it
  2. If there is no such bin, open a new one

- **First Fit**
  1. Try to place an item in the first bin that accommodates it
  2. If no such bin is found, open a new one

- **FFD (First Fit Decreasing)**
  Same as FF after sorting the items by decreasing order
Next Fit

- **Next Fit**
  1. Place each item in a single bin until an item does not fit in
  2. When an item don't fit, close it and open a new one

**Methodology**

Example followed by the analysis.
Next Fit (example)
Next Fit (analysis)

- The argument is that two consecutive bins are filled strictly more than $C'$
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The analysis is left as an exercise. Another option is to consider WorstFit.
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FF example
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The informal argument is that it is impossible to have two consecutive bins filled less than $C$. 
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Pictorial proof by contradiction:
**Proposition**

FF is a 2-approximation algorithm.
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- Assume FF uses $m$ bins (that corresponds to $SOL_{FF}$ in the optimization version of the problem).
- At least $(m-1)$ bins are more than half-full.
- $OPT \geq \sum s(a) > \frac{m-1}{2}$
- $2 \cdot OPT > m - 1$ and since $OPT$ and $m$ are integers, $2 \cdot OPT \geq m$
FF formal analysis

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Can we do (or even expect) better?
**Proposition**

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Can we do (or even expect) better?

**YES!**

- A refined analysis shows: $SOL_{FF} \leq \frac{17}{10} OPT$ (similarly for BestFit).
- A natural question is to look at other algorithms...
FFD example

First, sort the items.
FFD example
FFD example
FFD example
FFD example
FFD example
FFD example
FFD example
Remark: in this example the bins are all full, but it is not always the case!
We can show (but it is difficult) that:

- $SOL_{FFD} \leq \frac{11}{9}OPT + \frac{6}{9}$
- It is also possible to show that this bound is tight.

Does it contradict the inapproximation bound?
We can show (but it is difficult) that:

- \( SOL_{FFD} \leq \frac{11}{9} OPT + \frac{6}{9} \)
- It is also possible to show that this bound is tight.

Does it contradict the inapproximation bound?  
**NO!**

The result was established for the case \( OPT = 2 \)

\[
2 \cdot \frac{11}{9} + \frac{6}{9} = 3 + \frac{1}{9} \text{ bins}
\]

that shows that FFD is a \( \frac{3}{2} \)-approximation

For large values of \( n \), we can obtain much better approximation ratio (asymptotically)
Let analyze two particular cases of the problem.

- \( \delta \) is given
  Consider that all the item sizes are smaller than \( \delta \)

- \( q \) is given
  Consider that there are only \( q \) different sizes
### 1. FF with limited item sizes

We refine the approximation ratio of FF.

- $\delta$ is given

#### Claim 1

$$FF \leq (1 + 2\delta)OPT + 1$$

#### Proof

- if $\delta \geq \frac{1}{2}$ the result is immediate:
  $$FF \leq 2 \cdot OPT + 1 \leq (1 + 2\delta)OPT + 1$$

Thus, assume $\delta < \frac{1}{2}$
FF with limited item sizes (cont’d)

- \( \delta < \frac{1}{2} \)
- \((FF - 1)(1 - \delta) \leq OPT\)

Geometric argument.
FF with limited item sizes (cont’d)

- $\delta < \frac{1}{2}$
- $(FF - 1)(1 - \delta) \leq OPT$
  Geometric argument.

Thus, $FF \leq (1 + 2\delta)OPT + 1$

Can you say WHY?
FF with limited item sizes (detail)

- $(FF - 1)(1 - \delta) \leq OPT$
- $FF \leq \frac{1}{1-\delta}OPT + 1$
- $\frac{1}{1-\delta} \leq 1 + 2\delta$ for $\delta < \frac{1}{2}$
FF with limited item sizes (detail)

- \((FF - 1)(1 - \delta) \leq OPT\)

- \(FF \leq \frac{1}{1-\delta}OPT + 1\)

- \(\frac{1}{1-\delta} \leq 1 + 2\delta\) for \(\delta < \frac{1}{2}\)

\[FF \leq (1 + 2\delta)OPT + 1\]
2. FF with limited number of sizes

- \( q \) is given

**Claim 2**

the optimal number of bins can be found in time \( O(n^{2q+1}) \)
where \( n \) is the total number of items.

**Proof**

- Sort the items by size \( S_1, S_2, \ldots, S_q \)
  where \( |S_j| = n_j \) and \( \sum_{1 \leq j \leq q} n_j = n \)
- Let enumerate the number of possible combinations into a subset \( S_j \):
  it is bounded by \( O(n^q) \)
- Compute the optimal number of bins for each subset by Dynamic Programming.
  There are at most \( OPT \) steps, each costs less than \( O(n^{2q}) \)
  and obviously, \( OPT \leq n \)
The idea here is to use a smart encoding.

**Example**

Let consider the following instance:

- \((2, 4, 9, 3, 7, 9, 3, 2, 3)\)
- The corresponding multi-set \((q = 5)\) is \((2, 3, 4, 7, 9)\)
- We represent the encoding by a vector of dimension \(q\) as follows:
  - \((2, 3, 7, 3) \rightarrow (1, 2, 0, 1, 0)\)

This way, the number of subsets is in \(O(n^q)\) and not \(\Theta(2^n)\)
Combining both cases together...

- Consider an instance $\mathcal{I}$ of the general problem and $\epsilon$
  If all the item sizes are $\leq \frac{\epsilon}{2}$ then by Claim 1:
  $$\text{FF} (\mathcal{I}) \leq (1 + \epsilon)\text{OPT} (\mathcal{I}) + 1$$

- Assume that all the item sizes are $> \frac{\epsilon}{2}$
  By Claim 2, there exists a packing algorithm –call it $A(\mathcal{I})$– for which:
  $$\text{SOL}_A (\mathcal{I}) \leq (1 + \epsilon)\text{OPT} (\mathcal{I}) + 1$$
Construction of the combined approximation algorithm

Let introduce a parameter $x$ whose value will be determined later.

- Sort $\mathcal{I}$ in non-decreasing order.
- Split it into $\left\lceil \frac{n}{x} \right\rceil$ groups of $x$ elements each. Denote $\left\lceil \frac{n}{x} \right\rceil$ in short by $n_x$ and the i-th group by $G_i$.
- Pack $G_1$ in at most $x$ bins.
- Change all the sizes in $G_i$ (for $i \geq 2$) to the largest size in this group. Call this new instance $\mathcal{I}'$.
- Determine the optimal packing of $\mathcal{I}'$ by using the process of Claim 2.

Proposition

$OPT(\mathcal{I}') \leq OPT(\mathcal{I})$
Example

Let us consider the following instance $\mathcal{I}$
Example (cont’d)

- The transformed instance $\mathcal{I}'$

```
G_2
```
```
G_3
```
```
G_4
```
Another rounding

- Proof of: \( OPT(\mathcal{I}') \leq OPT(\mathcal{I}) \)

- Consider the new derived instance \( \mathcal{I}'' \) constructed as follows:
  - Remove the smallest group \( (G_{n_x}) \)
  - Change every element in group \( G_i \) for \( 1 \leq i \leq n_x - 1 \) to the smallest item in this group.
Example instance $\mathcal{I}$
Proof of:

\[ OPT(I') \leq OPT(I) \]

Clearly, \[ OPT(I'') \leq OPT(I) \]

WHY?
Analysis of the rounded algorithms

- Proof of:
  \[ \text{OPT}(\mathcal{I}') \leq \text{OPT}(\mathcal{I}) \]

- Clearly, \( \text{OPT}(\mathcal{I}'') \leq \text{OPT}(\mathcal{I}) \)
  \textbf{WHY?}

- Since \( \mathcal{I}'' \) has less elements and they are smaller.
Analysis of the rounded algorithms

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- \( \text{OPT}(\mathcal{I}') \leq \text{OPT}(\mathcal{I}'') \)
  WHY?
Analysis of the rounded algorithms

- Proof of:
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  WHY?
- Since \( \mathcal{I}'' \) has less elements and they are smaller.

- \( \text{OPT}(\mathcal{I}') \leq \text{OPT}(\mathcal{I}'') \)
  WHY?
- 1. \( \mathcal{I}' \) may have less elements:
   \[ |G_{n_x}| \leq |G_1| \] and all the other sets have the same size in both.
   2. \( \mathcal{I}' \) has a smaller total sum
   since \( \max G_{i+1} \leq \min G_i \) for \( 1 \leq n_x - 1 \)

\[ \text{OPT}(\mathcal{I}') \leq \text{OPT}(\mathcal{I}'') \leq \text{OPT}(\mathcal{I}) \]
We are almost at home!

- the running time of the algorithm is in $O(n^{2n_x+1})$
- its approximation ratio is:
  
  $SOL_A(I) \leq OPT(I) + x$

- We can then choose $x$
  
  $x = \lceil \epsilon \cdot \sum_{1 \leq i \leq n} s_i \rceil$

WHY?
We are almost at home!

- The running time of the algorithm is in $O(n^{2m} + 1)$
- Its approximation ratio is:
  $$SOL_A(I) \leq OPT(I) + x$$
- We can then choose $x$
  $$x = \lceil \epsilon \cdot \sum_{1 \leq i \leq n} s_i \rceil$$

**WHY?**
Because $\lceil \epsilon \cdot \sum_{1 \leq i \leq n} s_i \rceil \leq \epsilon \cdot OPT + 1$
Synthesis of the asymptotic-PTAS: the algorithm

1. we are given $\epsilon < 1$
2. split the instance into two parts of small $\leq \frac{\epsilon}{2}$ and large $> \frac{\epsilon}{2}$
3. round the large items of $\mathcal{I}'$ with $q = \lceil \epsilon \cdot \sum_{a \in \mathcal{I}'} s(a) \rceil$
4. determine the optimal packing of this rounded sub-instance
5. keep the same packing with the original values
6. pack the remaining small items using FirstFit

Notice that packing the small items can done without increasing the ratio since there is an area at most $\frac{\epsilon}{2}$ left in each bin, may be we will need one extra bin that will be only partially filled.
Final result

### Asymptotic PTAS

- The running time expressed in $\epsilon$ is:
  $$O(n^{\frac{4}{\epsilon^2} + 1})$$
  It is polynomial because $\epsilon$ is fixed.
- The approximation ratio is $(1 + \epsilon)OPT + 1$
Final remark: How to beat FFD?

- For beating FFD, we need to choose $\epsilon \leq \frac{2}{9}$
- As a consequence, the APTAS will have the following running time:
  \[ O\left(\frac{n^4}{\left(\frac{2}{9}\right)^2} + 1\right) = O\left(n^{82}\right) \]
- more than the number of atoms in the universe...